

# An Introduction to Semantic Subtyping

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# Outline

- 1 Motivations and goals.
- 2 Semantic subtyping.
- 3 Subtyping Algorithms.
- 4 Application to a language.
- 5 Extensions.

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# Goal

The goal is to show how to take your favourite type constructors

$\times, \rightarrow, \{\dots\}, \text{chan}(), \dots$

and add boolean combinators:

$\vee, \wedge, \neg$

so that they behave set-theoretically w.r.t.  $\leq$

## WHY?

Short answer: they are convenient and you need them to program XML in a typed language with **pattern matching**.

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# LONGER ANSWER: Patterns and $\vee$ , $\wedge$ , $\neg$ types

Let:

- $t = \{v \mid v \text{ value of type } t\}$
- $\{p\} = \{v \mid v \text{ matches pattern } p\}$

## ① Useful for typing:

$\text{match } e \text{ with } p_1 \rightarrow e_1 \mid p_2 \rightarrow e_2$

- To infer the type  $t_1$  of  $e_1$  we need  $t \wedge \{p_1\}$  (where  $e : t$ );
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- The type of the match is  $t_1 \vee t_2$ .

## ② Useful for programming:

$\text{map catalog with}$

$x : (\text{Car A } (\neg \text{Used} \vee \text{Guarantee})) \rightarrow x$

Select in *catalog* all the cars that if they are used then have a guarantee.

## ③ Useful for other paradigms:

a general technique to add subtyping to different paradigms:  
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# In details

$$t ::= B \mid t \times t \mid t \rightarrow t \mid t \vee t \mid t \wedge t \mid \neg t \mid 0 \mid 1$$

- Handling subtyping without combinators is easy:  
constructors do not mix, e.g.

$$\frac{S_1 \subseteq S_2 \quad S_3 \subseteq S_4}{S_1 \times S_3 \subseteq S_2 \times S_4}$$

- Subtyping relation is defined by induction on types
- Subtyping relation is reflexive and transitive

• Subtyping relation is closed under function application

• Subtyping relation is closed under product and sum

## Bottom types

Instead of defining the subtyping relation so that it conforms to the semantic of types, define the semantics of types and derive the subtyping relation.

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$$\begin{array}{c} s_2 \leq s_1 \quad t_1 \leq t_2 \\ s_1 \rightarrow t_1 \leq s_2 \rightarrow t_2 \end{array}$$

- With combinators is much harder:  
combinators distribute over constructors, e.g.

$$(s_1 \rightarrow t_1) \times (s_2 \rightarrow t_2) \leq (s_1 \times s_2) \rightarrow (t_1 \times t_2)$$

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$$(s \wedge t) \rightarrow z \geq (s \rightarrow z) \wedge (t \rightarrow z)$$

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- **None fully satisfactory.** (no negation, or no function types, or restrictions on unions and intersections, . . . )
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- ① Define a set-theoretic semantics of the types:

$$\llbracket \ ] : \text{Types} \longrightarrow \mathcal{P}(\mathcal{D})$$

- ② Define the subtyping relation as follows:

$$s \leq t \stackrel{\text{def}}{\iff} \llbracket s \rrbracket \subseteq \llbracket t \rrbracket$$

## KEY OBSERVATION 1:

The *model of types* may be independent from a *model of terms*

Hosoya and Pierce use the model of values:

$$\llbracket t \rrbracket_T = \{ v \mid \vdash v : t \}$$

Ok because the only values of XDuce are XML documents

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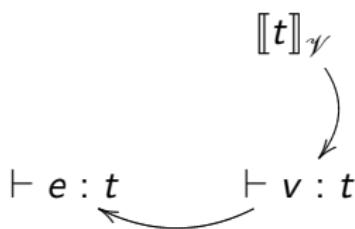
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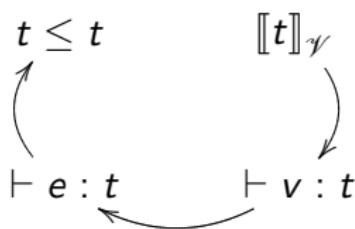


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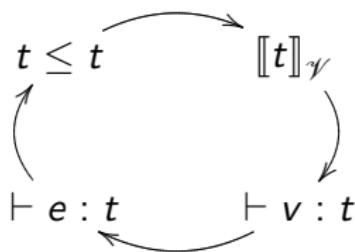


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$$t \leq s \iff \llbracket t \rrbracket_{\mathcal{V}} \subseteq \llbracket s \rrbracket_{\mathcal{V}} \quad \text{where} \quad \llbracket t \rrbracket_{\mathcal{V}} = \{v \mid \vdash v : t\}$$

No longer works with arrow types: values are  $\lambda$ -abstractions and need (sub)typing to be defined

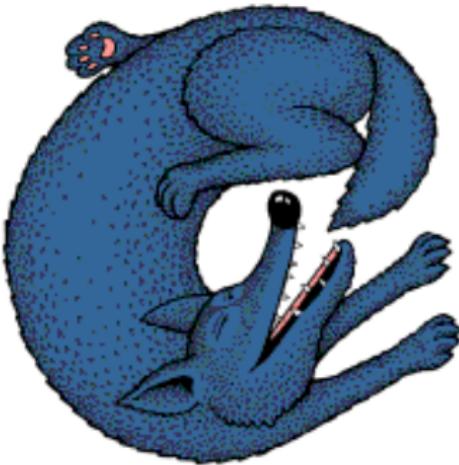


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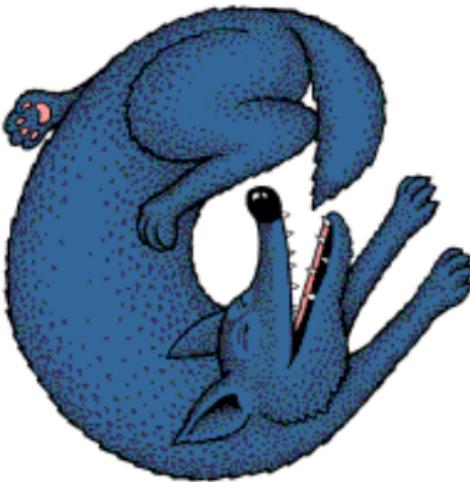


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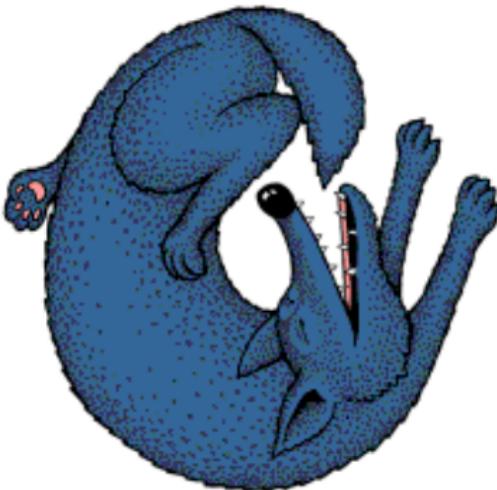


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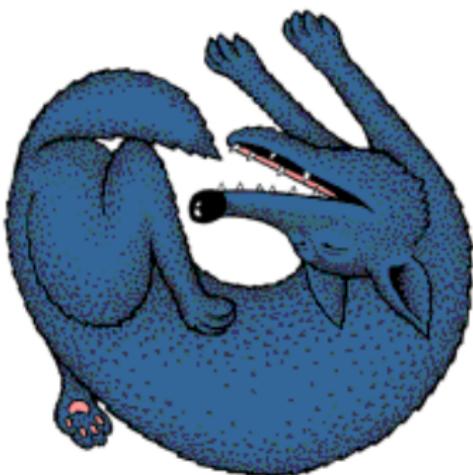


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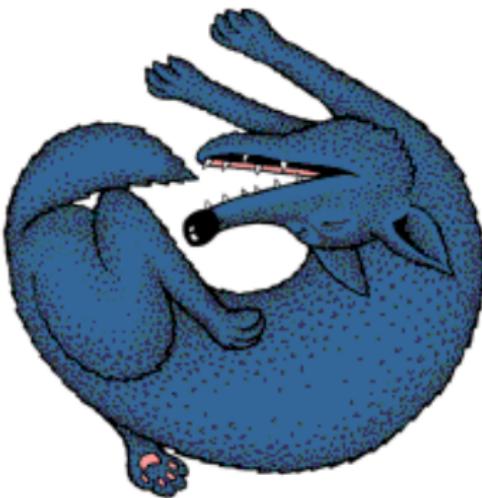


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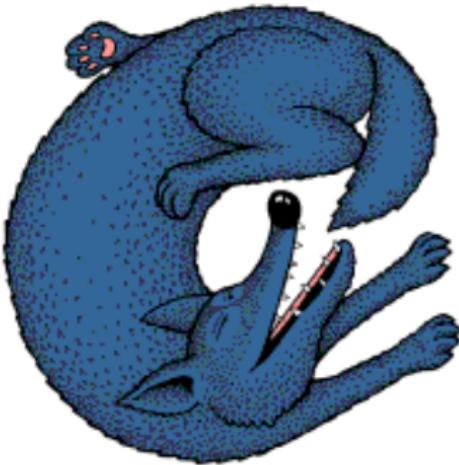


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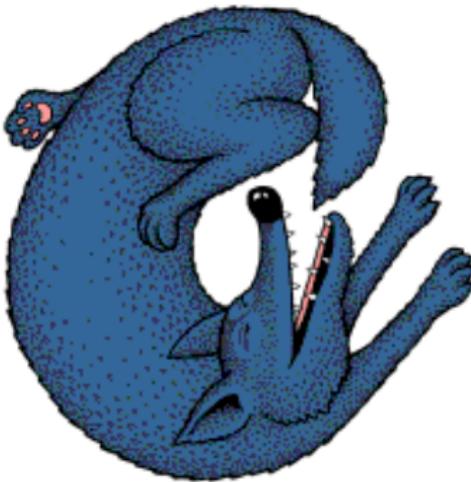


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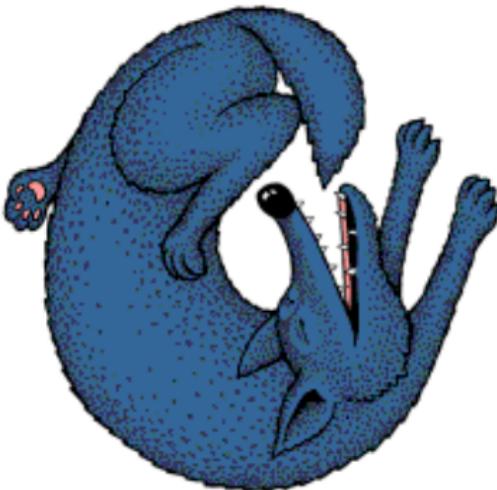


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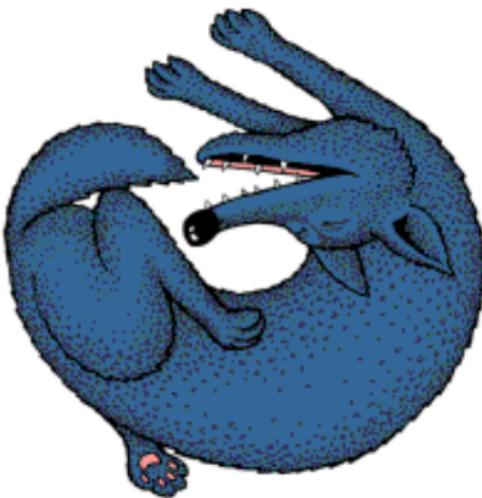


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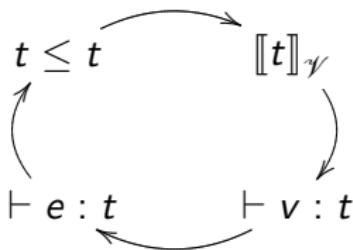


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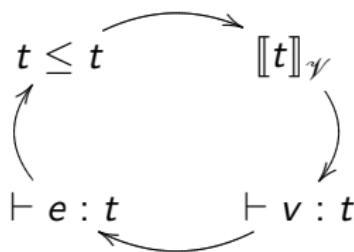
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$\llbracket t \rrbracket_{\mathcal{D}}$



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$$\begin{array}{ccc} & \xrightarrow{\hspace{1cm}} & \llbracket t \rrbracket_{\mathcal{D}} \\ t \leq t & \curvearrowleft & \llbracket t \rrbracket_{\mathcal{V}} \end{array}$$

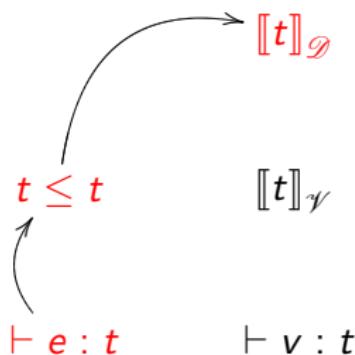
$$\vdash e : t \quad \vdash v : t$$

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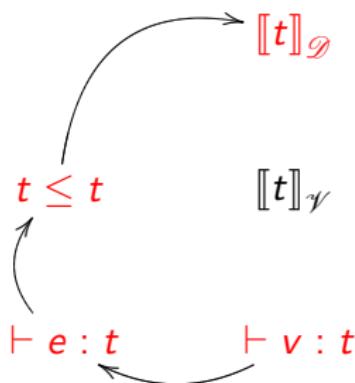


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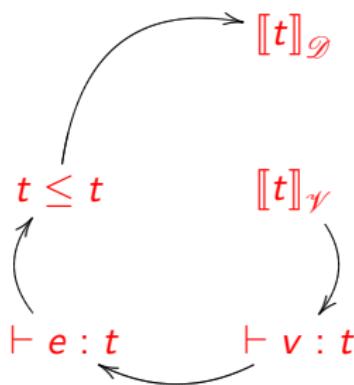


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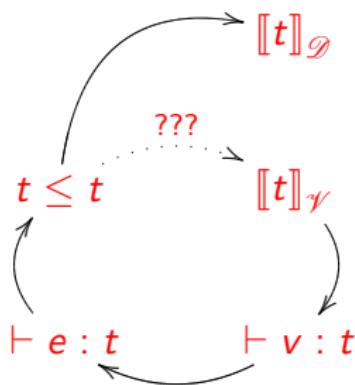


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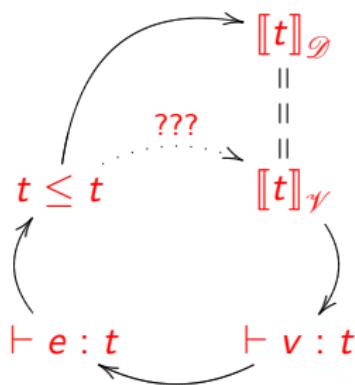


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Define when  $\llbracket \cdot \rrbracket : \text{Types} \longrightarrow \mathcal{P}(\mathcal{D})$  yields a *set-theoretic* model.

- Easy for the combinators:

$$\llbracket t_1 \vee t_2 \rrbracket = \llbracket t_1 \rrbracket \cup \llbracket t_2 \rrbracket$$

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$$\llbracket t_1 \times t_2 \rrbracket =$$

$$\llbracket t_1 \rightarrow t_2 \rrbracket =$$

Think semantically!

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# Intuition

$\llbracket t \rightarrow s \rrbracket = ???$

QUESTION: What is the type of  $t \rightarrow s$ ?

$\square$

as if

( $\cdot$ )

$$\llbracket t_1 \rightarrow s_1 \rrbracket \subseteq \llbracket t_2 \rightarrow s_2 \rrbracket \iff \mathcal{P}(\overline{\llbracket t_1 \rrbracket} \times \overline{\llbracket s_1 \rrbracket}) \subseteq \mathcal{P}(\overline{\llbracket t_2 \rrbracket} \times \overline{\llbracket s_2 \rrbracket})$$

# Intuition

$\llbracket t \rightarrow s \rrbracket = \{\text{functions from } \llbracket t \rrbracket \text{ to } \llbracket s \rrbracket\}$

PERMISSIONS  
as if  
()

$\llbracket \cdot \rrbracket$       as if       $(\cdot)$

$$\llbracket t_1 \rightarrow s_1 \rrbracket \subseteq \llbracket t_2 \rightarrow s_2 \rrbracket \iff \wp(\overline{\llbracket t_1 \rrbracket} \times \overline{\llbracket s_1 \rrbracket}) \subseteq \wp(\overline{\llbracket t_2 \rrbracket} \times \overline{\llbracket s_2 \rrbracket})$$

# Intuition

$$\llbracket t \rightarrow s \rrbracket = \{f \subseteq \mathcal{D}^2 \mid \forall (d_1, d_2) \in f. \ d_1 \in \llbracket t \rrbracket \Rightarrow d_2 \in \llbracket s \rrbracket\}$$

KEY OBSERVATION 2:



as if



$$\llbracket t_1 \rightarrow s_1 \rrbracket \subseteq \llbracket t_2 \rightarrow s_2 \rrbracket \iff \mathcal{P}(\overline{\llbracket t_1 \rrbracket} \times \overline{\llbracket s_1 \rrbracket}) \subseteq \mathcal{P}(\overline{\llbracket t_2 \rrbracket} \times \overline{\llbracket s_2 \rrbracket})$$

# Intuition

$$\llbracket t \rightarrow s \rrbracket = \mathcal{P}(\overline{\llbracket t \rrbracket} \times \overline{\llbracket s \rrbracket}) \quad (\text{ } \overline{X} \stackrel{\text{def}}{=} \text{complement of } X \text{ } )$$

KEY OBSERVATION 2:

$\llbracket \cdot \rrbracket$

as if

(\*)

$$\llbracket t_1 \rightarrow s_1 \rrbracket \subseteq \llbracket t_2 \rightarrow s_2 \rrbracket \iff \mathcal{P}(\overline{\llbracket t_1 \rrbracket} \times \overline{\llbracket s_1 \rrbracket}) \subseteq \mathcal{P}(\overline{\llbracket t_2 \rrbracket} \times \overline{\llbracket s_2 \rrbracket})$$

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$$\llbracket t \rightarrow s \rrbracket = \mathcal{P}(\overline{\llbracket t \rrbracket} \times \overline{\llbracket s \rrbracket}) \quad (*)$$

Impossible since it requires  $\mathcal{P}(\mathcal{D}^2) \subseteq \mathcal{D}$

## KEY OBSERVATION 2:

Accept every  $\llbracket \cdot \rrbracket$  that behaves w.r.t.  $\subseteq$  as if equation  $(*)$  held, namely

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and similarly for any boolean combination of arrow types.

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We need the model to state **how types are related** rather than **what the types are**

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# Technically ...

- ① Take  $\llbracket \_ \rrbracket : \mathbf{Types} \rightarrow \mathcal{P}(\mathcal{D})$  such that

$$\llbracket t_1 \vee t_2 \rrbracket = \llbracket t_1 \rrbracket \cup \llbracket t_2 \rrbracket$$

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[combinator semantics]

- ② Define  $\llbracket \cdot \rrbracket : \mathbf{Types} \rightarrow \mathcal{P}(\mathcal{D}^2 + \mathcal{P}(\mathcal{D}^2))$  as follows

$$\llbracket \text{Bival} \rrbracket \triangleq \llbracket \text{Bival} \rrbracket \times \llbracket \text{Bival} \rrbracket$$

$$\llbracket \text{B}[t_1 \rightarrow t_2] \rrbracket \triangleq \llbracket t_1 \rrbracket \times \llbracket t_2 \rrbracket \triangleq \mathcal{D}^2$$

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[non-commutative composition]

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⋮ [constructor semantics]

- ③ Models: instead of requiring  $\llbracket t \rrbracket = \mathbb{E}[\llbracket t \rrbracket]$ , accept  $\llbracket \_ \rrbracket \in \mathbb{E}[\llbracket \_ \rrbracket]$

$$(\lambda x : A \rightarrow B) \in \mathbb{E}[\llbracket \lambda x : A \rightarrow B \rrbracket]$$

↳ more general models

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↳ which is equivalent to  $\llbracket t \rrbracket = \mathbb{E}[t]$  since  $\mathbb{E}[t] = \emptyset \iff t = 0$

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# The main intuition

To characterize  $\leq$  all is needed is the test of emptiness

Indeed:  $s \leq t \Leftrightarrow \llbracket s \rrbracket \subseteq \llbracket t \rrbracket \Leftrightarrow \llbracket s \rrbracket \cap \overline{\llbracket t \rrbracket} = \emptyset \Leftrightarrow \llbracket s \wedge \neg t \rrbracket = \emptyset$

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$\llbracket \cdot \rrbracket$  and  $\mathbb{E}[\cdot]$  must have the same zeros

We relaxed our requirement but ...

... the model is still not valid

Is it possible to define  $\llbracket \cdot \rrbracket: \text{Types} \rightarrow \wp(\wp)$  that satisfies the model conditions, in particular a  $\llbracket \cdot \rrbracket$  such that  $\llbracket t \rrbracket = \emptyset \Leftrightarrow \mathbb{E}[t] = \emptyset$ ?

**YES: an example within two slides**

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# The role of $\llbracket E \rrbracket$

$\llbracket E \rrbracket$  characterizes the behavior of types (for what it concerns  $\leq$  one can consider  $\llbracket t \rrbracket = \llbracket E[t] \rrbracket$ ): it depends on the language the types are intended for.

Variations are possible. Our choice

$$\llbracket t_1 \rightarrow t_2 \rrbracket = \overline{\mathcal{P}(\llbracket t_1 \rrbracket \times \llbracket t_2 \rrbracket)}$$

accounts for languages that are:

① Non-deterministic

Admits functions in which  $(d, d_1)$  and  $(d, d_2)$  with  $d_1 \neq d_2$ .

② Partial and/or non-total

A function in  $\llbracket t \rightarrow t \rrbracket$  may be not total on  $\llbracket t \rrbracket$ .

③ Functions with side effects

④ Functions with type annotations

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$$\llbracket \vdash 0 \rrbracket = \text{functions diverging on } t$$

⇒  $\llbracket t \rrbracket \neq \emptyset$

⇒  $\llbracket t \rightarrow s \rrbracket \neq \emptyset$  (not total)

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③ *Overloaded*:

$$\llbracket (\lambda x y z) \rightarrow (s/t/s) \rrbracket \subseteq \llbracket (t \rightarrow s) \llbracket t \rightarrow s \rrbracket \rrbracket$$

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# Closing the circle

- ① Take any model  $(\mathcal{B}, \llbracket \cdot \rrbracket_{\mathcal{B}})$  to bootstrap the definition.

- ② Define

$$s \leq_{\mathcal{B}} t \iff \llbracket s \rrbracket_{\mathcal{B}} \subseteq \llbracket t \rrbracket_{\mathcal{B}}$$

- ③ Take any “appropriate” language  $\mathcal{L}$  and use  $\leq_{\mathcal{B}}$  to type it

$$\Gamma \vdash_{\mathcal{B}} e : t$$

- ④ Define a new interpretation  $\llbracket t \rrbracket_{\gamma} = \{v \in \mathcal{V} \mid \vdash_{\mathcal{B}} v : t\}$  and  
 $s \leq_{\gamma} t \iff \llbracket s \rrbracket_{\gamma} \subseteq \llbracket t \rrbracket_{\gamma}$

- ⑤ If  $\mathcal{L}$  is “appropriate” ( $\vdash_{\mathcal{B}} v : t \iff \forall_{\mathcal{B}} v : \neg t$ ) then  $\llbracket \cdot \rrbracket_{\gamma}$  is a model and

$$s \leq_{\mathcal{B}} t \iff s \leq_{\gamma} t$$

The circle is closed

# Closing the circle

- ① Take any model  $(\mathcal{B}, \llbracket \cdot \rrbracket_{\mathcal{B}})$  to bootstrap the definition.

- ② Define

$$s \leq_{\mathcal{B}} t \iff \llbracket s \rrbracket_{\mathcal{B}} \subseteq \llbracket t \rrbracket_{\mathcal{B}}$$

- ③ Take any “appropriate” language  $\mathcal{L}$  and use  $\leq_{\mathcal{B}}$  to type it

$$\Gamma \vdash_{\mathcal{B}} e : t$$

- ④ Define a new interpretation  $\llbracket t \rrbracket_{\mathcal{V}} = \{v \in \mathcal{V} \mid \vdash_{\mathcal{B}} v : t\}$  and  
 $s \leq_{\mathcal{V}} t \iff \llbracket s \rrbracket_{\mathcal{V}} \subseteq \llbracket t \rrbracket_{\mathcal{V}}$

- ⑤ If  $\mathcal{L}$  is “appropriate” ( $\vdash_{\mathcal{B}} v : t \iff \vdash_{\mathcal{B}} v : \neg t$ ) then  $\llbracket \cdot \rrbracket_{\mathcal{V}}$  is a model and

$$s \leq_{\mathcal{B}} t \iff s \leq_{\mathcal{V}} t$$

The circle is closed

# Closing the circle

① Take any model  $(\mathcal{B}, \llbracket \cdot \rrbracket_{\mathcal{B}})$  to bootstrap the definition.

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⑤ If  $\mathcal{L}$  is “appropriate” ( $\vdash_{\mathcal{B}} v : t \iff \vdash_{\mathcal{B}} v : \neg t$ ) then  $\llbracket \cdot \rrbracket_{\mathcal{V}}$  is a model and

$$s \leq_{\mathcal{B}} t \iff s \leq_{\mathcal{V}} t$$

The circle is closed

# Closing the circle

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 $s \leq_{\mathcal{V}} t \iff \llbracket s \rrbracket_{\mathcal{V}} \subseteq \llbracket t \rrbracket_{\mathcal{V}}$

⑤ If  $\mathcal{L}$  is “appropriate” ( $\vdash_{\mathcal{B}} v : t \iff \not\vdash_{\mathcal{B}} v : \neg t$ ) then  $\llbracket \cdot \rrbracket_{\mathcal{V}}$  is a model and

$$s \leq_{\mathcal{B}} t \iff s \leq_{\mathcal{V}} t$$

The circle is closed

# Closing the circle

① Take any model  $(\mathcal{B}, \llbracket \cdot \rrbracket_{\mathcal{B}})$  to bootstrap the definition.

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$$s \leq_{\mathcal{B}} t \iff s \leq_{\mathcal{V}} t$$

**The circle is closed**

# Exhibit a model

Does a model exists? (i.e. a  $\llbracket \cdot \rrbracket$  such that  $\llbracket t \rrbracket = \emptyset \iff \mathbb{E}[\llbracket t \rrbracket] = \emptyset$ )

YES: take  $(\mathcal{U}, \llbracket \cdot \rrbracket_{\mathcal{U}})$  where

$\mathcal{U}$ : least solution of  $X = X^2 + \mathcal{P}(X^2)$

$$\mathcal{U} = \bigcup_{n \in \mathbb{N}} \mathcal{U}_n$$

$$\mathcal{U}_n = \bigcup_{m \in \mathbb{N}} \mathcal{U}_{n,m}$$

$$\mathcal{U}_{n,m} = \bigcup_{k \in \mathbb{N}} \mathcal{U}_{n,m,k}$$

$$\mathcal{U}_{n,m,k} = \bigcup_{l \in \mathbb{N}} \mathcal{U}_{n,m,k,l}$$

It is a model:  $\mathcal{P}(\overline{\llbracket t \rrbracket_{\mathcal{U}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}}) = \emptyset \iff \mathcal{P}(\overline{\llbracket t \rrbracket_{\mathcal{U}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}}) = \emptyset$

It is the best model: for any other model  $\llbracket \cdot \rrbracket_{\mathcal{S}}$ ,

$$t_1 \leq_{\mathcal{S}} t_2 \Rightarrow t_1 \leq_{\mathcal{U}} t_2$$

# Exhibit a model

Does a model exists? (i.e. a  $\llbracket \cdot \rrbracket$  such that  $\llbracket t \rrbracket = \emptyset \iff \mathbb{E}[\llbracket t \rrbracket] = \emptyset$ )

YES: take  $(\mathcal{U}, \llbracket \cdot \rrbracket_{\mathcal{U}})$  where

①  $\mathcal{U}$  least solution of  $X = X^2 + \mathcal{D}_f(X^2)$

②  $\llbracket \cdot \rrbracket_{\mathcal{U}}$  is defined as

It is a model:  $\mathcal{D}_f(\overline{\llbracket t \rrbracket_{\mathcal{U}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}}) = \emptyset \iff \mathcal{D}(\overline{\llbracket t \rrbracket_{\mathcal{U}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}}) = \emptyset$

It is the best model: for any other model  $\llbracket \cdot \rrbracket_g$

$$t_1 \leq_g t_2 \Rightarrow t_1 \leq_{\mathcal{U}} t_2$$

# Exhibit a model

Does a model exists? (i.e. a  $\llbracket \cdot \rrbracket$  such that  $\llbracket t \rrbracket = \emptyset \iff \mathbb{E}[\llbracket t \rrbracket] = \emptyset$ )

YES: take  $(\mathcal{U}, \llbracket \cdot \rrbracket_{\mathcal{U}})$  where

①  $\mathcal{U}$  least solution of  $X = X^2 + \mathcal{P}_f(X^2)$

②  $\llbracket \cdot \rrbracket_{\mathcal{U}}$  is defined as:

$$\begin{aligned} \llbracket t \rrbracket_{\mathcal{U}} &= \{ s \in \mathcal{U} \mid \text{for all } u \in \mathcal{U}, \llbracket t \rrbracket_{\mathcal{U}} \times \llbracket s \rrbracket_{\mathcal{U}} \not\models u \} \\ &= \{ s \in \mathcal{U} \mid \text{for all } u \in \mathcal{U}, \llbracket t \rrbracket_{\mathcal{U}} \times \llbracket s \rrbracket_{\mathcal{U}} \models u \} \end{aligned}$$

It is a model:  $\mathcal{P}_f(\overline{\llbracket t \rrbracket_{\mathcal{U}}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}}) = \emptyset \iff \mathcal{P}(\overline{\llbracket t \rrbracket_{\mathcal{U}}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}}) = \emptyset$

It is the best model: for any other model  $\llbracket \cdot \rrbracket_g$

$$t \leq_g t \Rightarrow t \leq_{\mathcal{U}} t$$

# Exhibit a model

Does a model exists? (i.e. a  $\llbracket \cdot \rrbracket$  such that  $\llbracket t \rrbracket = \emptyset \iff \mathbb{E}[t] = \emptyset$ )

YES: take  $(\mathcal{U}, \llbracket \cdot \rrbracket_{\mathcal{U}})$  where

- ①  $\mathcal{U}$  least solution of  $X = X^2 + \mathcal{P}_f(X^2)$

- ②  $\llbracket \cdot \rrbracket_{\mathcal{U}}$  is defined as:

$$\llbracket t \rrbracket_{\mathcal{U}} = \emptyset \quad \llbracket u \rrbracket_{\mathcal{U}} = \emptyset \quad \llbracket \neg t \rrbracket_{\mathcal{U}} = \neg \llbracket t \rrbracket_{\mathcal{U}}$$

$$\llbracket s+t \rrbracket_{\mathcal{U}} = \llbracket s \rrbracket_{\mathcal{U}} \cup \llbracket t \rrbracket_{\mathcal{U}} \quad \llbracket s \cdot t \rrbracket_{\mathcal{U}} = \llbracket s \rrbracket_{\mathcal{U}} \cap \llbracket t \rrbracket_{\mathcal{U}}$$

$$\llbracket \lambda x. t \rrbracket_{\mathcal{U}} = \{x \in \mathcal{U} \mid \forall y \in \mathcal{U} \quad \llbracket t[x/y] \rrbracket_{\mathcal{U}} = \emptyset\}$$

It is a model:  $\mathcal{P}_f(\overline{\llbracket t \rrbracket_{\mathcal{U}}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}}) = \emptyset \iff \mathcal{P}(\overline{\llbracket t \rrbracket_{\mathcal{U}}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}}) = \emptyset$

It is the best model: for any other model  $\llbracket \cdot \rrbracket_{\mathcal{S}}$

$$t \leq_{\mathcal{S}} t \Rightarrow t \leq_{\mathcal{U}} t$$

# Exhibit a model

Does a model exists? (i.e. a  $\llbracket \cdot \rrbracket$  such that  $\llbracket t \rrbracket = \emptyset \iff E[t] = \emptyset$ )

YES: take  $(\mathcal{U}, \llbracket \cdot \rrbracket_{\mathcal{U}})$  where

①  $\mathcal{U}$  least solution of  $X = X^2 + \mathcal{P}_f(X^2)$

②  $\llbracket \cdot \rrbracket_{\mathcal{U}}$  is defined as:

$$\llbracket 0 \rrbracket_{\mathcal{U}} = \emptyset \quad \llbracket 1 \rrbracket_{\mathcal{U}} = \mathcal{U} \quad \llbracket \neg t \rrbracket_{\mathcal{U}} = \mathcal{U} \setminus \llbracket t \rrbracket_{\mathcal{U}}$$

$$\llbracket s \vee t \rrbracket_{\mathcal{U}} = \llbracket s \rrbracket_{\mathcal{U}} \cup \llbracket t \rrbracket_{\mathcal{U}} \quad \llbracket s \wedge t \rrbracket_{\mathcal{U}} = \llbracket s \rrbracket_{\mathcal{U}} \cap \llbracket t \rrbracket_{\mathcal{U}}$$

$$\llbracket s \times t \rrbracket_{\mathcal{U}} = \llbracket s \rrbracket_{\mathcal{U}} \times \llbracket t \rrbracket_{\mathcal{U}} \quad \llbracket t \rightarrow s \rrbracket_{\mathcal{U}} = \mathcal{P}_f(\overline{\llbracket t \rrbracket_{\mathcal{U}}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}})$$

It is a model:  $\mathcal{P}_f(\overline{\llbracket t \rrbracket_{\mathcal{U}}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}}) = \emptyset \iff \mathcal{P}(\overline{\llbracket t \rrbracket_{\mathcal{U}}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}}) = \emptyset$

It is the best model: for any other model  $\llbracket \cdot \rrbracket_g$

$$t_1 \leq_g t_2 \Rightarrow t_1 \leq_{\mathcal{U}} t_2$$

# Exhibit a model

Does a model exists? (i.e. a  $\llbracket \cdot \rrbracket$  such that  $\llbracket t \rrbracket = \emptyset \iff \mathbb{E}[t] = \emptyset$ )

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$$\llbracket 0 \rrbracket_{\mathcal{U}} = \emptyset \quad \llbracket 1 \rrbracket_{\mathcal{U}} = \mathcal{U} \quad \llbracket \neg t \rrbracket_{\mathcal{U}} = \mathcal{U} \setminus \llbracket t \rrbracket_{\mathcal{U}}$$

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It is a model:  $\mathcal{P}_f(\overline{\llbracket t \rrbracket_{\mathcal{U}}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}}) = \emptyset \iff \mathcal{P}(\overline{\llbracket t \rrbracket_{\mathcal{U}}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}}) = \emptyset$

It is the best model: for any other model  $\llbracket \cdot \rrbracket_g$

$$t_1 \leq_g t_2 \Rightarrow t_1 \leq_{\mathcal{U}} t_2$$

# Exhibit a model

Does a model exists? (i.e. a  $\llbracket \cdot \rrbracket$  such that  $\llbracket t \rrbracket = \emptyset \iff \mathbb{E}[t] = \emptyset$ )

YES: take  $(\mathcal{U}, \llbracket \cdot \rrbracket_{\mathcal{U}})$  where

①  $\mathcal{U}$  least solution of  $X = X^2 + \mathcal{P}_f(X^2)$

②  $\llbracket \cdot \rrbracket_{\mathcal{U}}$  is defined as:

$$\llbracket 0 \rrbracket_{\mathcal{U}} = \emptyset \quad \llbracket 1 \rrbracket_{\mathcal{U}} = \mathcal{U} \quad \llbracket \neg t \rrbracket_{\mathcal{U}} = \mathcal{U} \setminus \llbracket t \rrbracket_{\mathcal{U}}$$

$$\llbracket s \vee t \rrbracket_{\mathcal{U}} = \llbracket s \rrbracket_{\mathcal{U}} \cup \llbracket t \rrbracket_{\mathcal{U}} \quad \llbracket s \wedge t \rrbracket_{\mathcal{U}} = \llbracket s \rrbracket_{\mathcal{U}} \cap \llbracket t \rrbracket_{\mathcal{U}}$$

$$\llbracket s \times t \rrbracket_{\mathcal{U}} = \llbracket s \rrbracket_{\mathcal{U}} \times \llbracket t \rrbracket_{\mathcal{U}} \quad \llbracket t \rightarrow s \rrbracket_{\mathcal{U}} = \mathcal{P}_f(\overline{\llbracket t \rrbracket_{\mathcal{U}}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}})$$

It is a model:  $\mathcal{P}_f(\overline{\llbracket t \rrbracket_{\mathcal{U}}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}}) = \emptyset \iff \mathcal{P}(\overline{\llbracket t \rrbracket_{\mathcal{U}}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}}) = \emptyset$

It is the **best** model: for any other model  $\llbracket \cdot \rrbracket_{\mathcal{Q}}$

$$t_1 \leq_{\mathcal{Q}} t_2 \Rightarrow t_1 \leq_{\mathcal{U}} t_2$$

# Exhibit a model

Does a model exists? (i.e. a  $\llbracket \cdot \rrbracket$  such that  $\llbracket t \rrbracket = \emptyset \iff \mathbb{E}[t] = \emptyset$ )

YES: take  $(\mathcal{U}, \llbracket \cdot \rrbracket_{\mathcal{U}})$  where

①  $\mathcal{U}$  least solution of  $X = X^2 + \mathcal{P}_f(X^2)$

②  $\llbracket \cdot \rrbracket_{\mathcal{U}}$  is defined as:

$$\llbracket 0 \rrbracket_{\mathcal{U}} = \emptyset \quad \llbracket 1 \rrbracket_{\mathcal{U}} = \mathcal{U} \quad \llbracket \neg t \rrbracket_{\mathcal{U}} = \mathcal{U} \setminus \llbracket t \rrbracket_{\mathcal{U}}$$

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$$\llbracket s \times t \rrbracket_{\mathcal{U}} = \llbracket s \rrbracket_{\mathcal{U}} \times \llbracket t \rrbracket_{\mathcal{U}} \quad \llbracket t \rightarrow s \rrbracket_{\mathcal{U}} = \overline{\mathcal{P}_f(\llbracket t \rrbracket_{\mathcal{U}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}})}$$

It is a model:  $\mathcal{P}_f(\overline{\llbracket t \rrbracket_{\mathcal{U}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}}) = \emptyset \iff \mathcal{P}(\overline{\llbracket t \rrbracket_{\mathcal{U}} \times \overline{\llbracket s \rrbracket_{\mathcal{U}}}) = \emptyset$

It is the **best** model: for any other model  $\llbracket \cdot \rrbracket_{\mathcal{D}}$

$$t_1 \leq_{\mathcal{D}} t_2 \Rightarrow t_1 \leq_{\mathcal{U}} t_2$$

# Exhibit a model

Does a model exists? (i.e. a  $\llbracket \cdot \rrbracket$  such that  $\llbracket t \rrbracket = \emptyset \iff \mathbb{E}[t] = \emptyset$ )

YES: take  $(\mathcal{U}, \llbracket \cdot \rrbracket_{\mathcal{U}})$  where

- ①  $\mathcal{U}$  least solution of  $X = X^2 + \mathcal{P}_f(X^2)$
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It is the **best** model: for any other model  $\llbracket \cdot \rrbracket_{\mathcal{D}}$

$$t_1 \leq_{\mathcal{D}} t_2 \quad \Rightarrow \quad t_1 \leq_{\mathcal{U}} t_2$$

# Exhibit a model

Does a model exists? (i.e. a  $\llbracket \cdot \rrbracket$  such that  $\llbracket t \rrbracket = \emptyset \iff \mathbb{E}[t] = \emptyset$ )

YES: take  $(\mathcal{U}, \llbracket \cdot \rrbracket_{\mathcal{U}})$  where

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It is the **best** model: for any other model  $\llbracket \cdot \rrbracket_{\mathcal{D}}$

$$t_1 \leq_{\mathcal{D}} t_2 \quad \Rightarrow \quad t_1 \leq_{\mathcal{U}} t_2$$

# Subtyping Algorithms.

# Canonical forms

Every (recursive) type

$$t ::= B \mid t \times t \mid t \rightarrow t \mid t \vee t \mid t \wedge t \mid \neg t \mid 0 \mid 1$$

is equivalent (semantically, that is w.r.t.  $\leq$ ) to a type of the form:

$$\bigvee_{(P,N) \in \Pi} \left( \left( \bigwedge_{s \times t \in P} s \times t \right) \wedge \left( \bigwedge_{s \times t \in N} \neg(s \times t) \right) \right) \quad \bigvee_{(P,N) \in \Sigma} \left( \left( \bigwedge_{s \rightarrow t \in P} s \rightarrow t \right) \wedge \left( \bigwedge_{s \rightarrow t \in N} \neg(s \rightarrow t) \right) \right)$$

- Put it in disjunctive normal form, e.g.

$$(a_1 \wedge a_2 \wedge \neg a_3) \vee (a_4 \wedge \neg a_5) \vee (\neg a_6 \wedge \neg a_7) \vee (a_8 \wedge a_9)$$

- Transform to have only homogeneous intersections, e.g.

$$((a_1 \times a_2) \wedge \neg(a_3 \times a_4)) \vee (\neg(a_5 \rightarrow a_6) \wedge \neg(a_7 \rightarrow a_8)) \vee (a_9 \times a_9)$$

→ <https://mpri.citlab.org/2023/01/03/03-algorithms/>

# Canonical forms

Every (recursive) type

$$t ::= B \mid t \times t \mid t \rightarrow t \mid t \vee t \mid t \wedge t \mid \neg t \mid 0 \mid 1$$

is equivalent (semantically, that is w.r.t.  $\leq$ ) to a type of the form:

$$\bigvee_{(P,N) \in \Pi} \left( \left( \bigwedge_{s \times t \in P} s \times t \right) \wedge \left( \bigwedge_{s \times t \in N} \neg(s \times t) \right) \right) \quad \bigvee_{(P,N) \in \Sigma} \left( \left( \bigwedge_{s \rightarrow t \in P} s \rightarrow t \right) \wedge \left( \bigwedge_{s \rightarrow t \in N} \neg(s \rightarrow t) \right) \right)$$

- Put it in disjunctive normal form, e.g.

$$(a_1 \wedge a_2 \wedge \neg a_3) \vee (a_4 \wedge \neg a_5) \vee (\neg a_6 \wedge \neg a_7) \vee (a_8 \wedge a_9)$$

- Transform to have only homogeneous intersections, e.g.

$$(s_1 \times t_1) \wedge \neg(s_2 \times t_2) \vee (\neg(s_3 \rightarrow t_3) \wedge \neg(s_4 \rightarrow t_4)) \vee (s_5 \times t_5)$$

- Group negative and positive atoms in the intersections:

$$\bigvee_{(P,N) \in S} \left( \left( \bigwedge_{a \in P} a \right) \wedge \left( \bigwedge_{a \in N} \neg a \right) \right)$$

# Canonical forms

Every (recursive) type

$$t ::= B \mid t \times t \mid t \rightarrow t \mid t \vee t \mid t \wedge t \mid \neg t \mid 0 \mid 1$$

is equivalent (semantically, that is w.r.t.  $\leq$ ) to a type of the form:

$$\bigvee_{(P,N) \in \Pi} \left( \left( \bigwedge_{s \times t \in P} s \times t \right) \wedge \left( \bigwedge_{s \times t \in N} \neg(s \times t) \right) \right) \quad \bigvee_{(P,N) \in \Sigma} \left( \left( \bigwedge_{s \rightarrow t \in P} s \rightarrow t \right) \wedge \left( \bigwedge_{s \rightarrow t \in N} \neg(s \rightarrow t) \right) \right)$$

- Put it in disjunctive normal form, e.g.

$$(a_1 \wedge a_2 \wedge \neg a_3) \vee (a_4 \wedge \neg a_5) \vee (\neg a_6 \wedge \neg a_7) \vee (a_8 \wedge a_9)$$

- Transform to have only homogeneous intersections, e.g.

$$((s_1 \times t_1) \wedge \neg(s_2 \times t_2)) \vee (\neg(s_3 \rightarrow t_3) \wedge \neg(s_4 \rightarrow t_4)) \vee (s_5 \times t_5)$$

- Group negative and positive atoms in the intersections:

$$\bigvee_{(P,N) \in S} \left( \left( \bigwedge_{a \in P} a \right) \wedge \left( \bigwedge_{a \in N} \neg a \right) \right)$$

# Canonical forms

Every (recursive) type

$$t ::= B \mid t \times t \mid t \rightarrow t \mid t \vee t \mid t \wedge t \mid \neg t \mid 0 \mid 1$$

is equivalent (semantically, that is w.r.t.  $\leq$ ) to a type of the form:

$$\bigvee_{(P,N) \in \Pi} \left( \left( \bigwedge_{s \times t \in P} s \times t \right) \wedge \left( \bigwedge_{s \times t \in N} \neg(s \times t) \right) \right) \quad \bigvee_{(P,N) \in \Sigma} \left( \left( \bigwedge_{s \rightarrow t \in P} s \rightarrow t \right) \wedge \left( \bigwedge_{s \rightarrow t \in N} \neg(s \rightarrow t) \right) \right)$$

- Put it in disjunctive normal form, e.g.

$$(a_1 \wedge a_2 \wedge \neg a_3) \vee (a_4 \wedge \neg a_5) \vee (\neg a_6 \wedge \neg a_7) \vee (a_8 \wedge a_9)$$

- Transform to have only homogeneous intersections, e.g.

$$((s_1 \times t_1) \wedge \neg(s_2 \times t_2)) \vee (\neg(s_3 \rightarrow t_3) \wedge \neg(s_4 \rightarrow t_4)) \vee (s_5 \times t_5)$$

- Group negative and positive atoms in the intersections:

$$\bigvee_{(P,N) \in S} \left( \left( \bigwedge_{a \in P} a \right) \wedge \left( \bigwedge_{a \in N} \neg a \right) \right)$$

# Canonical forms

Every (recursive) type

$$t ::= B \mid t \times t \mid t \rightarrow t \mid t \vee t \mid t \wedge t \mid \neg t \mid 0 \mid 1$$

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# Subtyping decomposition

Some ugly formulas:

$$\bigwedge_{i \in I} t_i \times s_i \leq \bigvee_{i \in J} t_i \times s_i$$

$$\iff \forall J' \subseteq J. \left( \bigwedge_{i \in I} t_i \leq \bigvee_{i \in J'} t_i \right) \text{ or } \left( \bigwedge_{i \in I} s_i \leq \bigvee_{i \in J \setminus J'} s_i \right)$$

$$\bigwedge_{i \in I} t_i \rightarrow s_i \leq \bigvee_{i \in J} t_i \rightarrow s_i$$

$$\iff \exists j \in J. \forall I' \subseteq I. \left( t_j \leq \bigvee_{i \in I'} t_i \right) \text{ or } \left( I' \neq I \text{ et } \bigwedge_{i \in I \setminus I'} s_i \leq s_j \right)$$

# Decision procedure

$$s \leq t?$$

Recall that:

$$s \leq t \iff [\![s]\!] \cap \overline{[\![t]\!]} = \emptyset \iff [\![s \wedge \neg t]\!] = \emptyset \iff s \wedge \neg t = \mathbf{0}$$

Consider  $s \wedge \neg t$

Put it in canonical form

$$\bigvee_{\sigma} ((\sigma(s) \wedge \sigma(\neg t)) \rightarrow (\sigma(s) \wedge \neg \sigma(t))) \quad \bigvee_{\sigma} ((\sigma(s) \wedge \neg \sigma(t)) \rightarrow (\sigma(s) \wedge \neg \sigma(t)))$$

Product of two terms:  $\sigma(s) \wedge \sigma(\neg t)$  and  $\sigma(s) \wedge \neg \sigma(t)$

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# Application to a language.

# Language

|   |                         |
|---|-------------------------|
| $e ::= x$   | variable                |
| $\mu f(s_1 \rightarrow t_1; \dots; s_n \rightarrow t_n)(x).e$ | abstraction, $n \geq 1$ |
| $e_1 e_2$   | application             |
| $(e_1, e_2)$  | pair                    |
| $\pi_i(e)$  | projection, $i = 1, 2$  |
| $(x = e \in t)?e_1 : e_2$                                     | binding type case       |

# Typing

$$\frac{\Gamma \vdash e : s \leq_B t}{\Gamma \vdash e : t} \text{ (subsumption)}$$

$$\frac{(\forall i) \Gamma, (f : s_1 \rightarrow t_1 \wedge \dots \wedge s_n \rightarrow t_n), (x : s_i) \vdash e : t_i}{\Gamma \vdash \mu f^{(s_1 \rightarrow t_1; \dots; s_n \rightarrow t_n)}(x).e : s_1 \rightarrow t_1 \wedge \dots \wedge s_n \rightarrow t_n} \text{ (abstr)}$$

(for  $s_1 \equiv s \wedge t$ ,  $s_2 \equiv s \wedge \neg t$ )

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Consider:

$$\mu f^{(\text{Int} \rightarrow \text{Int}; \text{Bool} \rightarrow \text{Bool})}(x).(y = x \in \text{Int})?(y + 1):\text{not}(y)$$

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# Reduction

$$\begin{aligned}
 (\mu f^{(\dots)}(x).e)v &\rightarrow e[x/v, (\mu f^{(\dots)}(x).e)/f] \\
 (x = v \in t)?e_1 : e_2 &\rightarrow e_1[x/v] & \text{if } v \in t \\
 (x = v \notin t)?e_1 : e_2 &\rightarrow e_2[x/v] & \text{if } v \notin t
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where

$$v ::= \mu f^{(\dots)}(x).e \mid (v, v)$$

And we have

$$s \leq_{\mathcal{B}} t \iff s \leq_{\mathcal{V}} t$$

The circle is closed

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# Why does it work?

$$s \leq_{\mathcal{B}} t \iff s \leq_{\mathcal{V}} t \quad (1)$$

Equation (1) (actually,  $\Rightarrow$ ) states that the language is quite rich, since there always exists a value to separate two distinct types; i.e. its set of values is a model of types with “enough points”

For any model  $\mathcal{B}$ ,

$$s \not\leq_{\mathcal{B}} t \implies \text{there exists } v \text{ such that } \vdash v : s \text{ and } \nvdash v : t$$

In particular, thanks to multiple arrows in  $\lambda$ -abstractions:

$$\bigwedge_{i=1..k} s_i \rightarrow t_i \not\leq t$$

then the two types are distinguished by  $\mu f^{(s_1 \rightarrow t_1; \dots; s_k \rightarrow t_k)}(x).e$

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# Advantages for the programmer

The programmer does not need to know the gory details. All s/he needs to retain is

- ① Types are the set of values of that type
- ② Subtyping is set inclusion

Furthermore the property

$s \not\leq t \implies$  there exists  $v$  such that  $\vdash v : s$  and  $\nvdash v : t$   
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# Extensions.

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$$\llbracket \text{ref } t \rrbracket = \{ \text{ref } v \mid v \in \llbracket t \rrbracket \}$$

In practice equivalent to

$$\llbracket \text{ref } t \rrbracket = \begin{cases} \{\llbracket t \rrbracket\} & \text{if } \llbracket t \rrbracket \neq \emptyset \\ \emptyset & \text{otherwise} \end{cases} \quad (2)$$

Deduce the subtyping relation

$$(\bigwedge_{\text{ref } s \in P} \text{ref } s) \leq (\bigvee_{\text{ref } t \in N} \text{ref } t) \iff \begin{array}{l} \exists \text{ref } s \in P, s \simeq 0, \text{ or} \\ \exists \text{ref } s_1 \in P, \exists \text{ref } s_2 \in P, s_1 \not\simeq s_2, \text{ or} \\ \exists \text{ref } s \in P, \exists \text{ref } t \in N, s \simeq t \end{array}$$

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# lazy types

If we define  $t = \text{Int} \times t$  then  $t \simeq 0$ .

Use  $s = \text{Int} \times \text{lazy } s$ .

$$(\mu f^{(\text{Int} \rightarrow s)}(x).(x, \text{lazy}(f(x + 1))))0$$

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But each `lazy e` is identified by all the possible results it can return, namely  $\{v \mid e \rightarrow^* v\}$ , from which we deduce:

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Deduce the subtyping relation

$$\begin{aligned} (\bigwedge_{\text{lazy } s \in P} \text{lazy } s) \leq (\bigvee_{\text{lazy } t \in N} \text{lazy } t) &\iff \\ \exists \text{lazy } t \in N : \forall P' \subseteq P \left( \bigwedge_{\text{lazy } s \in P'} s \right) \leq t \end{aligned}$$

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# channel types

Really, no time to show it but ...

This theory applies to other paradigms, too.

For instance in a paper in LICS '05 it is applied to  $\pi$ -calculus.  
There you have nice things such as:

$$ch(t) \stackrel{\text{def}}{=} ch^-(t) \wedge ch^+(t)$$

{some a constructor}

$$ch^+(t_1) \vee ch^+(t_2) \leq ch^+(t_1 \vee t_2)$$

{the “and” rule for intersection}

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[the "and-or" introduction]

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[the "join operator" is interesting]

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[the “not equal” is interesting]

# Summarizing

$$\begin{aligned} \llbracket \mathbf{0} \rrbracket &= \emptyset; \llbracket \mathbf{1} \rrbracket = \mathcal{D}; \\ \llbracket t_1 \vee t_2 \rrbracket &= \llbracket t_1 \rrbracket \cup \llbracket t_2 \rrbracket; \\ \llbracket t_1 \wedge t_2 \rrbracket &= \llbracket t_1 \rrbracket \cap \llbracket t_2 \rrbracket; \\ \llbracket \neg t \rrbracket &= \mathcal{D} \setminus \llbracket t \rrbracket; \\ \llbracket t \rrbracket = \emptyset &\iff \mathbb{E}[\llbracket t \rrbracket] = \emptyset \end{aligned}$$

where the extensional interpretation associated to  $\llbracket \cdot \rrbracket$  is defined as:

$$\begin{aligned} \mathbb{E}[t \rightarrow s] &= \overline{\mathcal{P}(\llbracket t \rrbracket \times \llbracket s \rrbracket)} \\ \mathbb{E}[t \times s] &= \llbracket t \rrbracket \times \llbracket s \rrbracket \\ \mathbb{E}[\text{lazy } t] &= \mathcal{P}(\llbracket t \rrbracket) \\ \mathbb{E}[\text{ref } t] &= \begin{cases} \{\llbracket t \rrbracket\} & \text{if } \llbracket t \rrbracket \neq \emptyset \\ \emptyset & \text{otherwise} \end{cases} \\ \dots \end{aligned}$$

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# Conclusion

# La morale de l'histoire est . . .

If you have a strong semantic intuition of your favorite language and you want to add set-theoretic  $\vee$ ,  $\wedge$ ,  $\neg$  types then:

- ➊ Define  $\llbracket \cdot \rrbracket$  for your type constructors so that it matches your semantic intuition
- ➋ Find a model (any model).
- ➌ Use the subtype relation induced by the model to type your language. If the intuition was right, then the set of values is also a model, whence break it.

Then, if you want to add more features, repeat the process.

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If you have a strong semantic intuition of your favorite language and you want to add set-theoretic  $\vee$ ,  $\wedge$ ,  $\neg$  types then:

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- ➍ Use the set-theoretic properties of the model (actually of  $\mathbb{E}[\ ]$ ) to decompose the emptiness test for your type constructors, and hence derive a subtyping algorithm.
- ➎ Enjoy.

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# Addendum 1: a model may not exist

$$t = \text{int} \vee (\text{ref}(\text{int}) \wedge \text{ref}(t))$$

Is  $t$  equal to  $\text{int}$ ?

$$t = \text{int} \iff (\text{ref}(\text{int}) \wedge \text{ref}(t)) = \emptyset \iff t \neq \text{int}$$

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## Addendum 2: the real *abstr* typing rule

$$t \equiv (\bigwedge_{i=1..n} s_i \rightarrow t_i) \setminus (\bigvee_{j=1..m} s'_j \rightarrow t'_j) \not\leq \mathbf{0}$$

$$\frac{(\forall i) \Gamma, (f : t), (x : s_i) \vdash e : t_i}{\Gamma \vdash \mu f(s_1 \rightarrow t_1; \dots; s_n \rightarrow t_n)(x). e : t} \text{ (abstr)}$$

## Addendum 3: A different definition for $\mathbb{E}[\cdot]$

Note that according to the previous  $\mathbb{E}[\cdot]$ :

$$s \rightarrow t \leq \mathbf{1} \rightarrow \mathbf{1} \quad (3)$$

Every application is well typed. Add a distinguished  $\Omega$  to denote a runtime type error, modify

$$\mathbb{E}[t \rightarrow s] = \{f \subseteq \mathcal{D} \times (\mathcal{D} \cup \{\Omega\}) \mid \forall (d_1, d_2) \in f. d_1 \in \llbracket t \rrbracket \Rightarrow d_2 \in \llbracket s \rrbracket\}$$

(3) no longer holds since the constant map  $\neg s \mapsto \Omega$ , is in the left hand type but not in the right one.

$$\begin{aligned} \bigwedge_{i \in I} (t_i \rightarrow s_i) \leq \bigvee_{j \in J} (t'_j \rightarrow s'_j) &\iff \\ \exists j \in J. \left\{ \begin{array}{l} t'_j \leq \bigvee_{i \in I} t_i \wedge \\ \forall I' \subseteq I. (t'_j \leq \bigvee_{i \in I'} t_i) \vee (\bigwedge_{i \in I \setminus I'} s_i \leq s'_j) \end{array} \right. & \end{aligned}$$

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